Optimizing Doppler Velocity Estimation with Deep Learning Project 4, Deep Learning F24

- **Result:** Achieved 1% of the baseline model's parameters with slightly better RMSE.

Architectures Overview

- Baseline Model (SpectrVelCNNRegr):
 - 1. Serves as a benchmark for comparison.
 - 2. Uses basic ReLU activations and MaxPooling for downsampling.



- Residual-ReLU Regressor:
 - 1. Trained with two activation functions: LeakyReLU and SiLU.
 - substitute Pool with Convolutional Layer and GAP
 - 3. Added Dropout and BatchNorm for regularization to mitigate overfitting.



- Squeeze-Excite Residual-SiLU Regressor :
 - 1. Introduced Squeeze-and-Excitation (SE) blocks for channel-wise attention.
 - 2. Implemented versions with different activation functions: SiLU and LeakyReLU+1.54%.
 - 3. Utilized Global Average Pooling to efficiently reduce spatial dimensions.



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Overview

• Goal: Estimate the radial velocity of a golf ball using 6-channel spectrograms with CNN, aiming to minimize parameters while maintaining low RMSE. • Key Innovation: Introduced skip connections to enhance feature flow and reduce parameters. Two models were designed: one with residual connections and another with Squeeze-and-Excitation blocks, optimized with alternative activation functions (LeakyReLU, SiLU) and pooling strategies.



2. Introduced residual connections to prevent vanishing gradients and improve feature flow

4. Test hyper. para. influence on test rmse: Adam+41.89% - Kaiming+6.64% - SiLU+7.99%



Hyperparameters

- Learning rate: 1e-5
- **Epoch:** 500
- Batch size: 10
- Optimizer:
 - SGD: better generalization and final convergence quality, despite slower initial progress.
- Activations:
 - LeakyReLU: Reduces dead neurons,



It was decided to switch validation and test sets, in order to have a higher sample count on test set. Achieving a more reliable final evaluation.





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